

A Low Noise Amplifier Suitable for Biomedical Recording Analog Front-End in 65nm CMOS Technology

R. Nagulapalli, K. Hayatleh, S. Barker, A.A. Tammam, N. Yassine, B. Yassine, M. Ben-Esmael.

Abstract: This paper presents a fully integrated Front-end, low noise amplifier, dedicated to the processing of various types of bio-medical signals, such as Electrocardiogram (ECG), Electroencephalography (EEG), Axon Action Potential (AAP). A novel noise reduction technique, for an operational transconductance amplifier (OTA), has been proposed. This adds a current steering branch parallel to the differential pair, with a view to reducing the noise contribution by the cascode current sources. Hence, this reduces the overall input referred noise of the Low Noise Amplifier (LNA), without adding any additional power. The proposed technique implemented in 65nm CMOS technology achieves 30dB closed loop voltage gain, 0.05Hz lower cut-off frequency and 100MHz 3-dB bandwidth. It operates at 1.2V power supply and draws 1 μ A static current. The prototype described in this paper occupies 3300 μ m² silicon area.

Key Words: ECG, EEG, AAP, VT, VF.

1. Introduction: The number of deaths, because of cardiac arrhythmia, totals around 4 million worldwide [1]. The arrhythmias of ventricular origins, ventricular tachycardia (VT) or ventricular fibrillation (VF) are the leading causes of death by cardiac arrhythmia. Ventricular arrhythmia is an abnormal ECG rhythm and is responsible for 75%–85% of deaths in patients with heart disease. Most ventricular arrhythmias are caused by coronary heart disease, hypertension and cardiomyopathy, which lead to death if it not treated or diagnosed at an early stage [1]. VT is a fast rhythm of three or more, consecutive beats originating from the ventricles at a rate higher than 100 beats/min. VF is a severely abnormal heart rhythm, due to the lower heart chambers contracting in an unsynchronized manner. This results in having little or no blood pumped through the heart, leading to life-threatening health conditions [2].

Electrodes are used to sense ECG signals for processing it in the electrical domain. The ECG signal consist mainly of three components, actual differential ECG signal, the offset voltage introduced by the electrodes and common-mode interference from 50/60Hz power supply. The actual differential ECG signal that appears between the electrodes in any lead configuration is limited to 0.1-5 mV in magnitude and 0.05 Hz to 150 Hz in frequency. The magnitude of this ECG signal, coupled with the resolution required from the ECG signal, determines the dynamic range for the front-end. The frequency content of this signal determines the bandwidth of the analog front-end. The skin-electrode interface provides an additional DC offset of 300 mV which needs to be compensated so that the signal chain is not saturated. Additionally, the human body can pick up large interference signals from the power lines, fluorescent lights, and so forth. This interference can be manifest as either a normal-mode signal or a common-mode signal. The normal-mode interference can be mitigated by software, implemented with a 50-Hz/60-Hz notch filter.

The paper contains five sections. Section-I is the introduction. Section-II and Section-III are the LNA design challenges and existing techniques. Section-IV is the proposed split differential pair technique. section-V contains a summary of the simulation results of the prototype. Finally, section-VI summarises and concludes the paper.

2. ECG Analog Front-End requirements: ECG signals pose several challenges to the hardware. Mainly, the input referred noise of the transceiver should be of order of 10 μ V, to meet the stringent sensitivity requirements. To allow the device to be a wearable option, the transceiver should consume as little amount of power possible, using a low voltage power supply. Multi-electrode sensing is often desirable for this purpose. However, the problem with the multi-electrode system is cross-talk induced noise (common-mode noise) due to the interaction among the electrodes. Hence, a very high common mode rejection ratio (CMRR) is required. There have been several attempts to develop hardware for accurate ECG analysis and hardware and classification [3]. Fig. 1 shows the multi-electrode neural recording system. Electrodes are used to convert the biological signals into electrical signals and these signals are fed to the electrical part of the recording system. These electrical signals are large DC offset voltages that are mainly due to leakage of DC current (100pA) and a high impedance at the interface. To summarise, the challenges of the front-end low-noise amplifier design are low noise, high

gain, low form-factor while consuming a minimal power. This paper considers the reduction of the input-referred noise without increasing the power supply voltage.

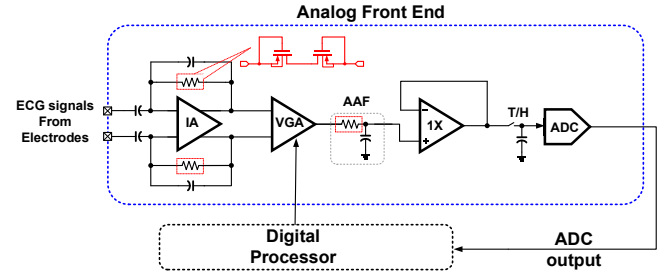


Fig. 1. ECG Analog Front-End block diagram [2].

3. Low Noise Amplifier (LNA): The low noise amplifier (LNA) is a high gain amplifier required for the frontend instrumentation amplifier (IA). LNA uses a capacitive feedback amplifier to amplify the signal while rejecting the DC offset from the electrodes. Fig. 2 (a) shows the amplifier feedback capacitor C_F and the input capacitor C_{IN} , where M_{P2} , M_{P1} form the feedback resistance. This defines the DC operating point by enabling the feedback in the low-frequency range, which we determined in our previous work [4]. The closed loop voltage gain is given by the ratio C_{IN} / C_F .

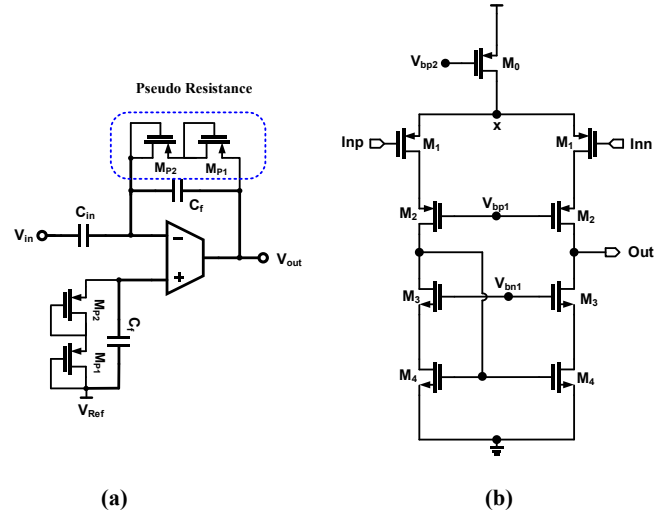


Fig. 2. (a) Closed loop LNA (b) Telescopic Cascode OTA (biasing not shown)

The input-referred noise of the LNA is contributed by the feedback resistors and OTA. The noise of the feedback resistor can be neglected due to low bandwidth. The overall noise of the LNA is mostly contributed by the OTA. Telescopic and folded cascode OTAs are the typical choices in LNAs, due to their high gain and simple dominate pole compensation nature. Since folded-cascode OTA generally use more current mirrors, discussed in our previous work [4], it's input referred offset is high due to random device mismatch. Therefore, a telescopic cascode is presented in this paper despite the fact the maximum voltage swing is less, in comparison with the folded cascode OTA. Fig. 2(b) shows the telescopic cascode OTA, where M_{1a} , M_{1b} forms the differential pair, while M_{2a} , M_{2b} , M_{3a} , M_{3b} comprise the current sources. The general expression for the Telescopic cascode voltage gain is given as follows [5]:

$$\frac{g_{m1}}{g_{m1} + \frac{g_{ds1}g_{ds2}}{g_{m1}} + \frac{g_{ds3}g_{ds4}}{g_{m4}}} \quad (1)$$

Input-referred noise is dominated by the differential pair transistors M_{1a} and the load PMOS current source M_{4a} . Cascode transistors M_{2a} and M_{3a} have little contribute since their sources are connected to another transistor drain, so that g_{m2} , g_{m3} will be decreased. Hence, there is negligible noise contribution. The spectral density of the thermal noise is given by [10]:

$$V_{n,thermal}^2 = 8KT\gamma \frac{1}{g_{m1}} \left(1 + \frac{g_{m2}}{g_{m1}}\right) \Delta f \quad (2a)$$

$$V_{Flicker}^2 = 2 \left[\frac{K_P}{C_{ox}W_1L_1} + \frac{K_N}{C_{ox}W_2L_2} \left(\frac{g_{m2}}{g_{m1}} \right)^2 \right] \frac{\Delta f}{f} \quad (2b)$$

where K is the Boltzmann Constant, T is the temperature in Kelvin, γ is the thermal noise coefficient which is $\sim 2/3$ for older CMOS technologies and >1 for sub micron technologies.

The input referred rms noise is calculated by the integrating of the above result within the intersted frequency band. As a result of increasing g_{m1} the noise will decrease additionally the contribution from the differential pair and current source will be reduced. g_{m1} can be increased either by increasing the bias current or by increasing the device size. The increase of the bias current will decrease the noise contribution of M_1 , while at the same time, it increases the contribution of M_4 . Prominent in older CMOS technologies, g_m increases with current linearly [5]. In the modern deep sub-micron technologies (from 65nm CMOS), the transistor g_m can be expressed as followin:

$$g_m = \frac{1}{2} \mu_n C_{ox} W E_{sat} \quad (3)$$

where C_{ox} is the oxide capacitance, μ_n is the carrier mobility, W is the width of the transistor and E_{sat} is the carrier velocity saturation electric field.

From equation (3) g_m increases linearly with current, for a low current range. g_m is almost independent of current (for the first order) and can only be increased by increasing the width. Fig. 3 shows the variations of g_m with changing values of current and width. The results show a small increase of g_m from $12\mu S$ to $14\mu S$ when doubling the current from $2\mu A$ to $4\mu A$ in a $5\mu m$ wide device. Whereas, increasing the width from $5\mu m$ to $10\mu m$ doubles g_m . Hence, current has less significant impact on the noise performance. In contrast the increase of the width will have significant improvement on the noise performance. Hence, it will increase the input paracitic capaciatnce (C_p) of the OTA. The increase of C_p will have the following impact on the transeiver performance. The input signal of the LNA will experience a potential division due to the C_{in} and C_p , thus limiting the available signal to LNA. Due to the weak nature of the bio-medical signal, a large value of C_p will effect the signal to noise ratio of the transeiver. The noise of the OTA will appear at the LNA input with a multiplication factor given by equation (4), which shows that a large value of C_p will increase the overall noise. The feedback factor of the LNA will decrease as result of large value of C_p [4].

$$\overline{V_{n,LNA}^2} = \overline{V_{n,OTA}^2} \frac{(C_{in} + C_f + C_p)^2}{C_{in}^2} \quad (4)$$

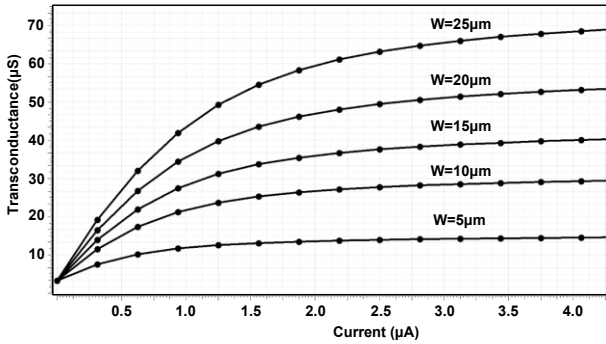


Fig. 3. Telescopic Opamp Transconductance Characteristics

It should be noted that increasing the input device size, with a view to minimise the noise, would not be effective method to decrease the noise. Several reserchers have proposed different methods to decrease noise [6-9], where the reduction in noise achieved was dependent on the technology and/or design optimization.

g_m/id methodology has been used to optimise the current mirror and differential pair transistors noise contribution [6]. The degenerated folded cascode LNA, provides the stacking inverter based LNA that is efficient but it inherits poor linearity [7-8]. There is a need for a special technique to reduce the noise of any architecture. This paper presents a novel technique to reduce the noise.

4. Proposed Low Noise Solution: The fundamental idea behind the proposal is as follows. In equation 2(b), g_{m1} should be maximized and g_{m2} should be minimized in order to minimize the noise. In the conventional telescopic cascode, the differential pair and cascode devices carries the same current. By modulating the bias current, both g_m 's change in the same direction, contrary to the requirement. low noise is achieved at the output by providing a different bias current for the differential pair (M_1) and the cascode current source (M_4).

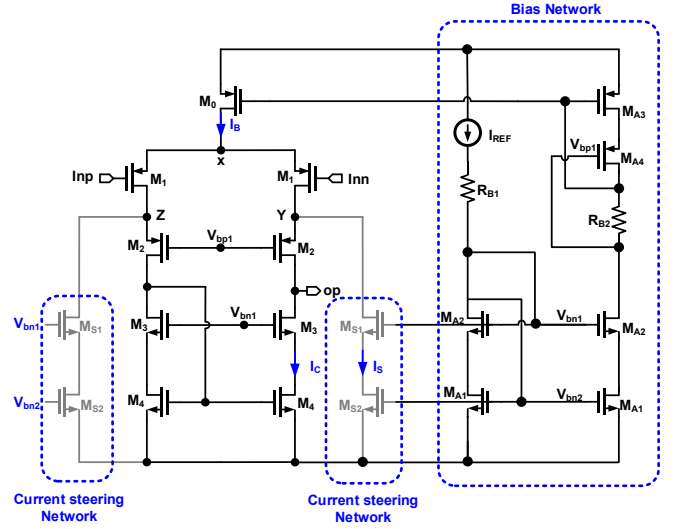


Fig. 4. Telescopic OTA with reduced input-referred noise

Fig. 4 shows the proposed technique which allows us to pull current out of the differential pair, in order to reduce the bias current in M_4 (the current source). Hence, this reduces the noise without compromising the current in M_1 . A standard cascode bias network, consisting of M_{A1} , M_{A2} , M_{A3} , M_{A4} , R_{B1} , R_{B2} , has been used to simplify the bias complications [5]. Generally, the differential pair current ($I_B/2$) will be set by the unity gain bandwidth (UGB) requirements or noise contribution. M_4 current is $(I_B/2 - I_S)$ minimized by adjusting the steering current (I_S). Therefore, this minimizes the contribution of M_4 . M_{S1} and M_{S2} form the cascode current steering device. While M_{S2} contributes additional noise, it can be optimized, by reducing additional noise, without affecting any other parameters of the opamp. This is achieved by using it as a current source. The transconductance of the devices can be expressed as:

$$g_{m1} = \sqrt{u_n c_{ox} I_B \left(\frac{W}{L} \right)_1} \quad g_{m4} = \sqrt{2u_n c_{ox} \left(\frac{I_B}{2} - I_S \right) \left(\frac{W}{L} \right)_4} \quad (5)$$

$$g_{mS2} = \sqrt{2u_n c_{ox} I_S \left(\frac{W}{L} \right)_{S2}} \quad (6)$$

The overall input-referred noise, including M_{S2} , can be expressed by substituting the expressions above into the equation below:

$$V_{in}^2 = 8KT\gamma \frac{1}{g_{m1}} \left(1 + \frac{g_{m4}}{g_{m1}} + \frac{g_{mS2}}{g_{m1}} \right) \quad (7)$$

$$V_{in}^2 = \frac{4KT\gamma}{\sqrt{u_n c_{ox} I_B \left(\frac{W}{L} \right)_1}} \left(1 + \sqrt{\frac{I_B - 2I_S}{I_B} \left(\frac{W}{L} \right)_4} + \sqrt{\frac{2I_S}{I_B} \left(\frac{W}{L} \right)_{S2}} \right) \quad (8)$$

Equation 8 shows a trade off between the noise contribution of M_4 and M_{S2} , but since the steering current is low, the M_{S2} noise contribution is low, while the M_4 noise contribution is high. Similiarly, when the split current is high, M_{S2} noise contribution is high, while M_4 noise contribution is low. Hence, there will be an optimal steering current which can be expressed by finding the derivative of equation (5). However, this will be very complicated and less intuitive to implement and it may not be correct due to submicron technology noise factor γ and full noise equations being unknown. Hence, we designed an amplifier with $1\mu A$ bias current through M_0 and swept the steering current source from 0 to $0.5\mu A$ (M_1 carries half of the M_0 current). Fig. 5 shows the low frequency noise spectral density versus split current. This paper covers thermal noise, but omits reviewing flicker noise, thereby minimizing the complication. The proposed design in this paper

minimises both noise types. Theoretically, the input referred noise, due to the split current (I_s), will decrease because M_4 contributes low noise when split current is high (mentioned above). Note this trend continues towards $0.175\mu\text{A}$. Furthermore, the current above $0.175\mu\text{A}$ will lead to an overall input referred noise, that increases with current I_s . This is due to the increase in the M_{S2} noise (Fig. 4) which dominates the decrease in the M_4 noise. It should be noted that the optimal I_s value depends on the technology parameters. Additionally, current I_s has a direct effect on the open loop gain of the OTA. This is due to the small signal current of transistor M_1 experiencing a division at node Y. A small current will flow into M_2 and M_{S1} . Hence, the signal current flow into the output will be slightly reduced, as well as the gain. For the usual case, the impedance of M_2 is $1/g_{m2}$, which is very small compared with the cascode impedance ($g_{ms1} \cdot r_{os1} \cdot r_{os2}$), which leads to a reduction in the gain.

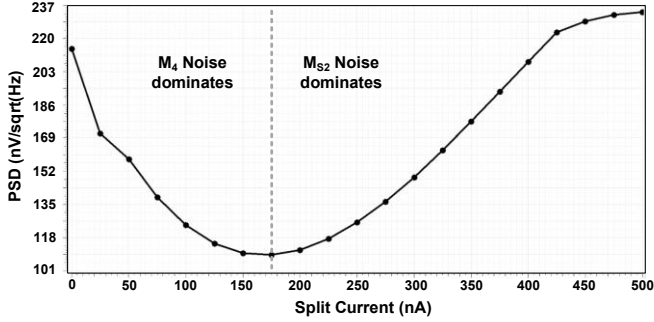


Fig. 5. Telescopic OTA with reduced input-referred noise

The effective small signal g_m can be expressed as $g_{m1} \frac{g_{m2}}{g_{m2} + \frac{g_{dss1} g_{dss2}}{g_{ms1}}}$, because M_1 signal current will be divided into two components, at node Y. Effective cascode conductance at the output node can be derived as $\frac{g_{ds3} g_{ds4}}{g_{m3}} + \frac{g_{ds2} g_{ds1}}{g_{m2}}$. Hence, by using effective transconductance and output conductance, the voltage gain can be expressed as follows.

$$\text{Gain} = \frac{g_{m1} \frac{g_{m2}}{g_{m2} + \frac{g_{dss1} g_{dss2}}{g_{ms1}}}}{\frac{g_{ds3} g_{ds4}}{g_{m3}} + \frac{g_{ds2} g_{ds1}}{g_{m2}}} \quad (9)$$

Since the split current is very high, M_{S2} carries a larger current than M_2 . This will reduce the impedance of the split current source (M_{S2}) and the gain will be derived from conventional means. To reduce the effect of I_s on the voltage gain, the impedance of the current steering network should be very high, hence the signal current flowing into current steering network is much less. To reduce this effect, the current steering network, with the cascode current source, is formed by M_{S1}, M_{S2} , rather than with M_{S2} only.

5. Implementaion Details: To demonstrate the proposed noise reduction technique, the LNA Front-end has been implemented in 65nm CMOS TSMC technology. The circuit design functions at 1.2V power supply voltage and draws $1\mu\text{A}$ current at room temperature. The aim is to achieve a LNA voltage Gain of 30dB, with selected capacitors C_{in}, C_f having capacitances of 3pF and 0.1pF respectively. To achieve an upper cut-off frequency $\sim 0.05\text{Hz}$, the feedback Pseudo resistance formed by M_{P2} and M_{P1} should be larger than $30T\Omega$. Figure 6 shows the resistance variation versus the voltage swing across the pseudo resistance. The transistors sizes of M_{P2} and M_{P1} are selected so that the resistance values are larger than that of the required, with a view to make the cut-off frequency less than 0.05Hz. The open loop gain of the OTA is 82dB, which is sufficient to give 0.01% accuracy and the phase margin is 72° , which indicates very stable closed loop operation, fig. 7 shows the frequency response of the opamp. Fig. 8 shows the simulated closed loop gain of the LNA. The simulated results show the mid-band gain is equal to 30dB, the lower cut-off frequency equal to $\sim 0.05\text{Hz}$ and the upper cut-off frequency equal to 100KHz, to process high frequency biomedical signals (see Figure 7). The upper cut-off frequency depends on the ratio of the input differential pair of the g_m and the load capacitance (the input capacitance of the VGA)[10].

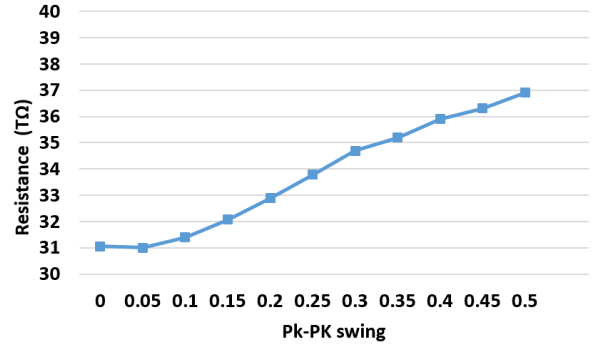


Fig. 6. Simulated resistance of the pseudo resistance.

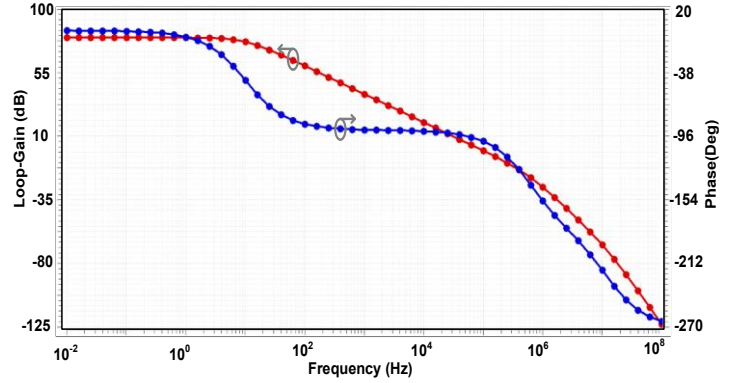


Fig. 7. Simulated Frequency response of the opamp.

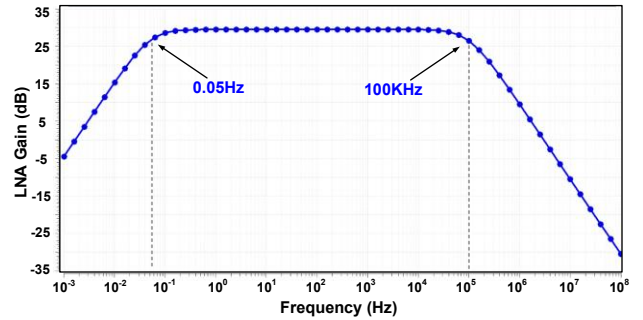


Fig. 8. Frequency response of the amplifier.

Fig. 9 shows the simulated input referred noise power spectral density (PSD) of the proposed and conventional cascode opamp. As described in the section 3, setting the value for the split current to $0.175\mu\text{A}$ achieves optimal noise performance. The PSD of the proposed design is 3dB lower than the cascode opamp, across the frequency band of interest. The flicker noise corner frequency is 35 KHz, the integrated RMS noise is $\sim 9.85\mu\text{V}$ for the cascode opamp, whereas for the proposed design, it is $6.9\mu\text{V}$, which is 30% better. Due to the weak amplitude of the signal, the LNA needs a high linearity to process, hence reducing the power supply and the common mode coupling. The total harmonic distortion (THD) has been simulated by varying the input signal amplitude with the maximum value of 4mV of the input amplitude. The THD was below 0.1%, but beyond 4mV amplitude and degraded rapidly. This was due to the OTA transistors experiencing a significant percentage of the signal swing compared to the operating point. A very reasonable 0.5% of the THD would process most signals [6]. Fig. 10 shows the simulated THD versus input amplitude. Figure 11 shows the layout of the proposed LNA, which occupies $1512\mu\text{m}^2$ active silicon area.

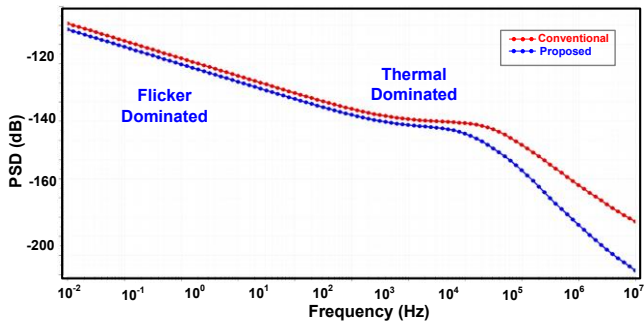


Fig. 9. Input-referred noise of the Amplifier

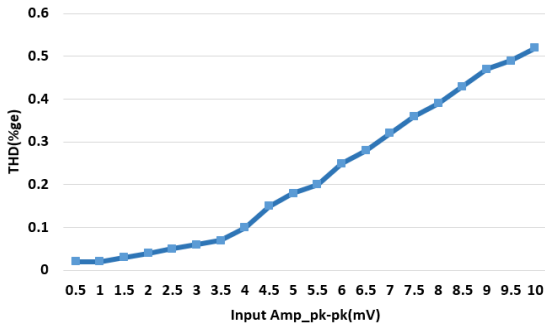


Fig. 10. THD versus applied input amplitude.

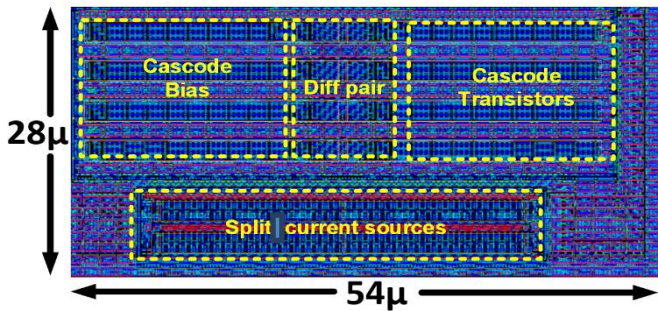


Fig. 11. Layout of the proposed circuit.

6. Conclusion: This paper presents a technique to reduce the input referred noise of the OTA by decreasing the Cascode current source gm, without increasing the power dissipation. A current splitting branch will reduce the Cascode devices current for any given bias current. The implementation in 65nm and post layout simulations, with Spectre simulator, shows that 30% noise reduction and 30dB voltage gain. The LNA draws 1μA current from 1.2V power supply.

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