

Reliability improvement and risk reduction by inequalities and segmentation

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Abstract

The paper introduces new domain-independent methods for improving reliability and reducing risk based on algebraic inequalities and chain-rule segmentation.

Two major advantages of algebraic inequalities for reducing risk have been demonstrated: (i) ranking risky prospects in the absence of any knowledge related to the individual building parts and (ii) reducing the variability of a risk-critical critical output parameter. The paper demonstrates a highly counter-intuitive result derived by using inequalities: if no information about the component reliability characterising the individual suppliers is available, purchasing components from a single supplier or from the smallest possible number of suppliers maximises the probability of a high-reliability assembly.

The paper also demonstrates the benefits from combining domain-independent methods and domain-specific knowledge for achieving risk reduction in several unrelated domains: decision-making, manufacturing, strength of components and kinematic analysis of complex mechanisms. In this respect, the paper introduces the chain rule segmentation method and applies it to reduce the risk of computational errors in kinematic analysis of complex mechanisms. The paper also demonstrates that combining the domain-independent method of segmentation and domain-specific knowledge in stress analysis leads to a significant reduction of the internal stresses and reduction of the risk of overstress failure.

Keywords: risk reduction; reliability improvement; domain-independent methods; inequalities, segmentation

1. Introduction

For many decades, the focus of the risk research has been exclusively on identifying risks, risk assessment and risk management rather than general methods for reliability improvement and risk reduction. While a great deal of agreement exists about the necessary common steps of risk assessment (Aven, 2016) and they can be considered to be domain-independent, there is insufficient research on general methods for reducing risk that work in various unrelated domains.

There is a strong perception that effective risk reduction can be delivered solely by using methods offered by the specific domains, without resorting to a general risk reduction

methodology. As a result, in textbooks on mechanical engineering and design of machine components, for example, (Budynas and Nisbett 2015; Childs, 2014; Thompson, 1999; French, 1999; Samuel and Weir, 1999; Collins, 2003; Norton, 2006; Pahl and Beitz, 2007), there is no reference to general methods for improving reliability and reducing the risk of failure of mechanical components.

Even in standard reliability textbooks (e.g. Lewis,1996; Ebeling, 1997; O'Connor 2002; Dhillon 2017; Modarres et al, 2017) there is a surprising lack of discussion related to domain-independent methods for improving reliability and reducing risk. The discussion is limited to few popular domain-independent methods for risk reduction such as: implementing redundancy, derating, eliminating a common cause, reducing variability, robust design, simplification and condition monitoring.

Recently, a number of new domain-independent methods and principles for improving reliability and reducing risk have been presented in (Todinov, 2019). The objective of the present paper is to extend the work on new domain-independent methods for risk reduction. This has been done by introducing new domain-independent methods for improving reliability and reducing risk based on algebraic inequalities and chain-rule segmentation.

Strength of components and kinematic analysis of complex mechanisms are mature and well-developed fields (Hearn 1985; Budynas, 1999; Gere and Timoshenko, 1999; Budynas and Nisbett 2015; Collins 2003; Norton, 2006; Uicker et al, 2017; Dicker et al, 2003; Sandor and Erdman, 1984). Despite this, to the best of our knowledge, nowhere in standard textbooks related to these fields, have the ideas of segmenting external loads and chain rule segmentation been used to reduce risk. In this respect, the paper demonstrates the benefits from combining domain-independent methods and domain-specific knowledge for achieving risk reduction in mature areas such as strength of components and kinematic analysis of complex mechanisms.

By using inequalities, the paper also demonstrates the significant benefits from combining domain-independent methods and domain-specific knowledge for risk reduction in decision-making and manufacturing. In these specific domains, the paper demonstrates the big potential of non-trivial algebraic inequalities in ranking risky prospects in complete absence of knowledge related to key parameters. There are a number of useful non-trivial algebraic inequalities such as the Arithmetic mean – Geometric mean (AM-GM) inequality, Cauchy-Schwartz inequality, the rearrangement inequality, the Chebyshev's inequality, Jensen's inequality, Muirhead's inequality, etc. Non-trivial algebraic inequalities have been discussed extensively in (Steele, 2004; Cloud et al. 1998; Engel 1998; Hardy et al., 1999; Kazarinoff,

1961; Pachpatte 2005). In probability theory, well-known non-trivial inequalities are the Tchebyshev's inequality, Markov's inequality, Boole's inequality, Bonferroni inequalities and Jensen's inequality. Some of these inequalities have been used in physics (Rastegin, 2012) and reliability theory (Ebeling, 1997) for obtaining lower and upper bound on the system reliability by using minimal cut sets and minimal path sets.

Despite the existence of a well-developed theory of non-trivial algebraic inequalities, there is a clear lack of discussion related to their application to reducing risk. In engineering design, the application is *mainly confined to trivial inequalities*. Design variables are required to satisfy various trivial design inequalities in order to guarantee that a number of failure modes will be eliminated and the design will perform its required functions (Samuel and Weir, 1999). Trivial inequality constraints have, for example, been introduced in (Ning-Cong et al., 2013) for describing the dependency of interval variables into a non-probabilistic model. Trivial inequalities, obtained by solving with respect to one of the variables have been used for specifying the upper bound of the lineal density of Poisson-distributed flaws to guarantee a probability of clustering below a maximum acceptable level (Todinov 2005).

Why are inequalities important for reliability improvement and risk reduction?

While the equalities express a state of equivalence, equilibrium and absence of transition, inequalities express ranking for the compared alternatives. In addition, inequalities do not normally require any knowledge related to the values of the controlling variables.

Suppose that two different system configurations are built by using the same set of n components with performance characteristics (e.g. reliabilities) x_1, x_2, \dots, x_n that are *unknown*. Let the performance of the first configuration be given by the function $f(x_1, \dots, x_n)$ while the performance of the second configuration be given by $g(x_1, \dots, x_n)$. If an equality of the type

$$f(x_1, \dots, x_n) > g(x_1, \dots, x_n)$$

could be proved, this would mean that the performance (e.g. reliability) of the first configuration is superior to the performance of the second configuration. Then the first system configuration can be selected and the risk of failure reduced in the absence of any knowledge related to the reliabilities of the parts building the systems. The possibility of making a correct ranking of two competing systems/processes under a complete absence of knowledge about the reliabilities of their building parts, constitutes a formidable advantage of algebraic inequalities. This advantage was demonstrated in Todinov (2019), where inequalities, proved by a direct algebraic manipulation, have been used for ranking the reliabilities of systems in the case where the reliabilities of their components are unknown.

This advantage will also be demonstrated in this paper with the application of the Muirhead's inequality for ranking risky prospects.

The next major advantage of the non-trivial algebraic inequalities as a domain-independent method for reducing risk can be found in their capacity to produce sharp bounds related to uncertainty associated with reliability-critical design parameters (e.g. material properties, dimensions, loads). In many cases, the actual values of the reliability-critical parameters are unknown or are associated with large variability. If a bound can be determined related to existing epistemic or aleatoric uncertainty, the design could be complied with this worst possible bound and a number of failure modes could be avoided.

Such a case is present for mechanical properties from multiple sources where the proportions with which the sources are present in the common pool of properties are unknown. Determining a sharp upper bound for the variation of properties helps to improve the robustness of the design. Consequently, inequalities producing such sharp bounds could yield reliability improvement and risk reduction.

Another major advantage of algebraic inequalities is that they work well in limiting the uncertainty associated with the variation of a critical output parameter and this application will be demonstrated in the manuscript.

2. Using the Muirhead's inequality for improving reliability and reducing risk

Consider a real-world example where three suppliers A_1 , A_2 and A_3 , produce high-reliability components of the same type, with probabilities x_1 , x_2 and x_3 , which are unknown. Probability x_i means that only a fraction x_i of the components produced by supplier i are of high-reliability and the rest are not. In the case of suspension automotive springs for example, this means that only a fraction x_i of the manufactured suspension springs can last for more than 600000 cycles if tested on a specially designed test rig and the rest of the springs fail significantly below this limit.

If two components are to be purchased and installed in an assembly, the question of interest is: which strategy maximises the probability that both components will be highly reliable?: (i) purchasing the two components from the same supplier or (ii) purchasing the two components from different suppliers. At a first glance, it seems that either of these

strategies could be chosen because the probabilities x_1 , x_2 and x_3 of high-reliability components characterising the suppliers are unknown. Surprisingly, this common-sense conclusion is incorrect.

The probability of purchasing two high-reliability components from the same supplier is: $p_1 = (1/3)x_1^2 + (1/3)x_2^2 + (1/3)x_3^2$ and is composed of the probabilities of three mutually exclusive events: (i) the probability $(1/3)x_1^2$ that supplier A_1 will be selected and both components purchased from A_1 will be highly reliable; (ii) the probability $(1/3)x_2^2$ that supplier A_2 will be selected and both components purchased from A_2 will be highly reliable and (iii) the probability $(1/3)x_3^2$ that supplier A_3 will be selected and both components purchased from A_3 will be highly reliable.

Accordingly, the probability of purchasing two high-reliability components from two different suppliers is $p_2 = (1/3)x_1x_2 + (1/3)x_1x_3 + (1/3)x_2x_3$.

The probability is composed of the probabilities of three mutually exclusive events: (i) the probability

$$(1/3) \times (1/2)x_1x_2 + (1/3) \times (1/2)x_2x_1 = (1/3)x_1x_2$$

that suppliers A_1 and A_2 will be randomly selected and both components purchased from A_1 and A_2 will be of high reliability; (ii) the probability $(1/3)x_1x_3$ that suppliers A_1 and A_3 will be randomly selected and both components purchased from A_1 and A_3 will be of high reliability and (iii) the probability $(1/3)x_2x_3$ that suppliers A_2 and A_3 will be randomly selected and both components purchased from A_2 and A_3 will be of high reliability.

The question is reduced to comparing the probabilities p_1 and p_2 . Consequently, the problem is reduced to proving (or disproving) the inequality $p_1 > p_2$

The last inequality follows from the general Muirhead's inequality (2), which is discussed next.

Muirhead's inequality: If the sequence $\{a\}$ majorizes the sequence $\{b\}$ and x_1, x_2, \dots, x_n are non-negative, the inequality

$$\sum_{sym} x_1^{a_1} x_2^{a_2} \dots x_n^{a_n} \geq \sum_{sym} x_1^{b_1} x_2^{b_2} \dots x_n^{b_n} \quad (2)$$

holds (Hardy et al, 1999).

Consider the two non-increasing sequences $a_1 \geq a_2 \geq \dots \geq a_n$ and $b_1 \geq b_2 \geq \dots \geq b_n$ of positive real numbers. The sequence $\{a\}$ is said to majorize the sequence $\{b\}$ if the following conditions are fulfilled:

$$a_1 \geq b_1; a_1 + a_2 \geq b_1 + b_2; \dots; a_1 + a_2 + \dots + a_{n-1} \geq b_1 + b_2 + \dots + b_{n-1};$$

$$a_1 + a_2 + \dots + a_{n-1} + a_n = b_1 + b_2 + \dots + b_{n-1} + b_n \quad (3)$$

For any set of non-negative numbers x_1, x_2, \dots, x_n , a symmetric sum is defined as

$\sum_{sym} x_1^{a_1} x_2^{a_2} \dots x_n^{a_n}$ which, when expanded, includes $n!$ terms. Each term is formed by a distinct

permutation of the elements of the sequence a_1, a_2, \dots, a_n . Thus, if $\{a\} = [2, 1, 0]$ then

$$\sum_{sym} x_1^2 x_2^1 x_3^0 = x_1^2 x_2 + x_1^2 x_3 + x_2^2 x_1 + x_2^2 x_3 + x_3^2 x_1 + x_3^2 x_2$$

If $\{a\} = [2, 0, 0]$, then

$$\sum_{sym} x_1^2 x_2^0 x_3^0 = 2x_1^2 + 2x_2^2 + 2x_3^2$$

Consider now the set of non-negative numbers x_1, x_2, x_3 and the sequences $\{a\} = [2, 0, 0]$ and $\{b\} = [1, 1, 0]$. Clearly, the sequence $\{a\} = [2, 0, 0]$ majorizes the sequence $\{b\} = [1, 1, 0]$ because the conditions (3) are fulfilled:

$$2 \geq 1; 2 + 0 \geq 1 + 1 \text{ and } 2 + 0 + 0 \geq 1 + 1 + 0.$$

According to the Muirhead's inequality (2):

$$2 \times (x_1^2 + x_2^2 + x_3^2) \geq 2(x_1 x_2 + x_1 x_3 + x_2 x_3)$$

Dividing both sides of the last inequality by the positive constant $3!$ leads to

$$p_1 = (1/3)x_1^2 + (1/3)x_2^2 + (1/3)x_3^2 \geq p_2 = (1/3)x_1 x_2 + (1/3)x_1 x_3 + (1/3)x_2 x_3 \quad (4)$$

According to inequality (4), $p_1 \geq p_2$ therefore purchasing both components from a single, randomly selected supplier is the better strategy, resulting in a higher probability that both components will be high-reliability components. This is a surprising and highly counter-intuitive result. After all, the percentages of high-reliability components characterising the suppliers are unknown.

Unexpected as it may seem, the conclusion has been confirmed by a Monte Carlo simulation. Consider three suppliers A, B and C , characterised by probabilities of high-reliability components $a_1 = 0.9$, $a_2 = 0.4$ and $a_3 = 0.3$. The Monte Carlo simulation based on one million trials yields 0.35 for the probability of two high-reliability components if a single

supplier is randomly selected and 0.25 for the probability of two high-reliability components if two suppliers are randomly selected. These values coincide with the values evaluated from the left and right hand side of (4).

The basic idea behind the simulation of purchasing two components from a randomly selected supplier and testing the components for high-reliability is done within a loop of ten million trials. The pseudo-code fragment is shown next:

```
a=[0.9, 0.4, 0.3]
n=3; num_trials=100000000;
count=0;

for i=1 to num_trials do
{
  sup_no=[n*rnd()]+1;

  x=rnd(); y=rnd();

  if(x<=a[sup_no] and y<=a[sup_no]) then count=count+1;
}
probability=count/num_trials;
```

A supplier is selected randomly with the statement `sup_no=[n*rnd()]+1`; where `[n*rnd]` is the greatest integer part that does not exceed `n*rnd()` and `rnd()` is a function that returns a random number from the interval (0,1). The probabilities of a high-reliability component are specified in the array `a[]`. In the test case, `a[0.9, 0.4, 0.3]` has been specified for the three suppliers. The test for two high-reliability components is performed by the conditional statement

```
if(x<=a[sup_no] and y<=a[sup_no]) then count =count+1;
```

where `x` and `y` are two random numbers from the interval (0,1). If the compound condition `x<=a[sup_no] and y<=a[sup_no]` is true, this means that both components are high-reliability components in which case the counter `count` of two high-reliability components is incremented. If the compound condition is false, the counter `count` is not incremented.

Finally, the probability of purchasing two high-reliability components from a randomly selected supplier is obtained by dividing the content of the counter to the number of trials.

Simulating purchasing of two high-reliability components from two randomly selected suppliers is done in a similar fashion and details will be omitted. First, a supplier is randomly selected, then from the remaining two suppliers one more supplier is randomly selected.

The same technique based on reducing to the Muirhead's general inequality can be extended for n different suppliers.

The probability of purchasing two high-reliability components from a randomly selected supplier is $p_1 = \frac{1}{n} \sum_{i=1}^n x_i^2$. Accordingly, the probability of purchasing two high-reliability

components from two randomly selected suppliers is $p_2 = \frac{2}{n(n-1)} \sum_{i<j} x_i x_j$.

Since the sequence $\{a\} = [2, 0, 0, \dots, 0]$ (containing n elements) majorizes the sequence $\{b\} = [1, 1, 0, \dots, 0]$ (also containing n elements), according to the Muirhead's inequality (2):

$$(n-1)! \times \sum_{i=1}^n x_i^2 \geq (n-2)! \times 2 \times \sum_{i<j} x_i x_j$$

Dividing both sides of the last inequality by the positive number $n!$ yields

$$p_1 = \frac{1}{n} \sum_{i=1}^n x_i^2 \geq p_2 = \frac{2}{n(n-1)} \sum_{i<j} x_i x_j \quad (5)$$

The left hand side of (5) is the probability of purchasing two high-reliability components from a randomly selected single supplier while the right hand side of (5) is the probability of purchasing two high-reliability components from two distinct, randomly selected suppliers.

Muirhead's inequality can also be applied for a larger number of purchased components. If, for example, three components are to be purchased from three suppliers ($n = 3$) and installed in an assembly, the question of interest is to choose between several competing strategies: a) purchasing the three components from a single, randomly selected supplier; b) purchasing the three components from three different suppliers or c) purchasing the three components from two randomly selected suppliers. Suppose that the suppliers are characterised by probabilities x_1 , x_2 and x_3 of producing high-reliability components. Because the sequence $\{a\} = [3, 0, 0]$ majorizes the sequence $\{b\} = [1, 1, 1]$, the next inequality follows immediately from the Muirhead's inequality (2):

$$(n-1)! \times (x_1^3 + x_2^3 + x_3^3) \geq n! \times x_1 x_2 x_3 \quad (6)$$

By dividing both sides of (6) to $n!$ ($n=3$), inequality (6) transforms into

$$\frac{1}{3} x_1^3 + \frac{1}{3} x_2^3 + \frac{1}{3} x_3^3 \geq x_1 x_2 x_3 \quad (7)$$

The left hand side of inequality (7) $\frac{1}{3} x_1^3 + \frac{1}{3} x_2^3 + \frac{1}{3} x_3^3$ is the probability of purchasing three high-reliability components from a randomly selected supplier. The right hand side of

inequality (7) is the probability $x_1x_2x_3$ of purchasing three high-reliability components from three separate suppliers.

Since the sequence $\{a\}=[3,0,0]$ also majorizes the sequence $\{c\}=[2,1,0]$, the following inequality follows immediately from the Muirhead's inequality (2):

$$(n-1)! \times (x_1^3 + x_2^3 + x_3^3) \geq x_1^2x_2 + x_1^2x_3 + x_2^2x_1 + x_2^2x_3 + x_3^2x_1 + x_3^2x_2 \quad (8)$$

Dividing both sides of (8) by $3!$ ($n=3$), gives

$$\begin{aligned} (1/3)x_1^3 + (1/3)x_2^3 + (1/3)x_3^3 \geq (1/3) \times [(1/2)x_1^2x_2 + (1/2)x_1^2x_3] + \\ (1/3) \times [(1/2)x_2^2x_1 + (1/2)x_2^2x_3] + (1/3) \times [(1/2)x_3^2x_1 + (1/2)x_3^2x_2] \end{aligned} \quad (9)$$

The left hand side of inequality (9) gives the probability of purchasing three high-reliability components from a randomly selected single supplier. The right hand side of inequality (9) gives the probability of purchasing three high-reliability components from two randomly selected suppliers.

Suppose that the fractions of high-reliability components characterising the three suppliers are $x_1 = 0.9$, $x_2 = 0.75$ and $x_3 = 0.25$. The Monte-Carlo simulation based on 10 million trials resulted in probabilities $p_1 = 0.389$ and $p_2 = 0.26$ of purchasing three high-reliability components from a randomly selected single supplier and from two randomly selected suppliers, correspondingly. The left and right part of the inequality (9) yields $p_1 = 0.389$ and $p_2 = 0.26$ for the same probabilities, which illustrates the validity of inequality (9).

Finally, since the sequence $\{a\}=[2,1,0]$ majorizes the sequence $\{c\}=[1,1,1]$, the following inequality follows immediately from the Muirhead's inequality (2):

$$x_1^2x_2 + x_1^2x_3 + x_2^2x_1 + x_2^2x_3 + x_3^2x_1 + x_3^2x_2 \geq n! x_1x_2x_3 \quad (10)$$

Dividing both sides of (10) by $3!$ ($n=3$), gives

$$\begin{aligned} (1/3) \times [(1/2)x_1^2x_2 + (1/2)x_1^2x_3] + (1/3) \times [(1/2)x_2^2x_1 + (1/2)x_2^2x_3] \\ + (1/3) \times [(1/2)x_3^2x_1 + (1/2)x_3^2x_2] \geq x_1x_2x_3 \end{aligned} \quad (11)$$

The left hand side of inequality (11) yields the probability of purchasing three high-reliability components from two randomly selected suppliers. The right hand side of inequality (11) yields the probability of purchasing three high-reliability components from three randomly selected suppliers.

For three suppliers are characterised by the probabilities $x_1 = 0.9$, $x_2 = 0.75$ and $x_3 = 0.25$ of selecting a high-reliability component, The Monte-Carlo simulation based on 10 million trials

resulted in probabilities $p_2 = 0.26$ and $p_3 = 0.169$ of purchasing three high-reliability components from two randomly selected suppliers and from the three suppliers, correspondingly.

The left and right hand part of inequality (11) yield $p_2 = 0.26$ and $p_3 = 0.169$ for the same probabilities, which illustrates the validity of the inequality (11).

The same reasoning can be applied for any number of purchased components.

In summary, if no information is available about the components reliability characterising the separate suppliers, the best strategy is to purchase the components from a single supplier or from the smallest possible number of suppliers.

The same reasoning can be applied for any number of purchased components.

In summary, if no information is available about the components reliability characterising the separate suppliers, the best strategy is to purchase the components from a single supplier or from the smallest possible number of suppliers.

This section also demonstrates an important technique in using inequalities to improve reliability and reduce risk. It consists of giving appropriate meaning to the abstract variables in the derived inequalities, closely related to reliability improvement and risk reduction.

2. Using inequalities for bounding deviations of reliability-critical parameters

This section features a powerful method for improving reliability by limiting the deviations of reliability-critical parameters caused by errors associated with the design variables.

Estimating the absolute error associated with a particular quantity in the case where the average values of the design variables determining the quantity are known is a standard procedure from calculus, based on total differential. Indeed, consider an output quantity z which is a smooth function $z = g(x_1, x_2, \dots, x_n)$ of n variables (parameters) x_1, \dots, x_n , whose nominal (specified) values x_{1m}, \dots, x_{nm} are known in advance. Suppose that the values x_1, \dots, x_n of the parameters vary around the specified nominal values x_{1m}, \dots, x_{nm} with the small quantities $\Delta x_1, \dots, \Delta x_n$. The absolute error Δz associated with the output quantity z is then determined from the total differential

$$\Delta z = \frac{\partial g}{\partial x_1} \Big|_{x_1=x_{1m}} \Delta x_1 + \dots + \frac{\partial g}{\partial x_n} \Big|_{x_n=x_{nm}} \Delta x_n \quad (12)$$

which relates the absolute error Δz of $z = g(x_1, \dots, x_n)$ at the nominal values of the specified parameters (x_{1m}, \dots, x_{nm}) to the errors $\Delta x_1, \dots, \Delta x_n$ associated with the independent variables x_1, \dots, x_n at these nominal values.

In order to evaluate the absolute error Δz from (12), the values of the partial derivatives at the point (x_{1m}, \dots, x_{nm}) must be known.

Consider now the case where the nominal values x_{1m}, \dots, x_{nm} of the independent variables x_1, \dots, x_n are unknown. The question of interest is to select the nominal values x_{1m}, \dots, x_{nm} in such a way that the absolute error Δz of the output quantity z is minimised. If the absolute error is bounded in this way, it is guaranteed that the reliability-critical parameter cannot exceed a dangerous value and reliability cannot be compromised.

This important question can be answered by presenting the error Δz of the output quantity as a function $f(x_1, \dots, x_n) = 0$ of n variables and minimising this function under the constraint

$$z = g(x_1, x_2, \dots, x_n)$$

which is effectively the function describing the output quantity.

According to the theory of multivariable optimisation (McCallum W.G., Hughes-Hallett D., Gleason A. M. et al., 2005), at the point of extremum, the equation:

$$\mathbf{grad} f(x_1, \dots, x_n) = \lambda \mathbf{grad} g(x_1, \dots, x_n) \quad (13)$$

and the equation

$$g(x_1, \dots, x_n) = 0 \quad (14)$$

must be satisfied, where λ is a constant of proportionality. These conditions are then used to derive the points at which the extremum is reached and also to evaluate the extremum. This approach will be illustrated by an application example from manufacturing.

Suppose that pieces of a particular material with volumes $V=7062 \text{ mm}^3$ are delivered for a subsequent re-melting and processing. The pieces have a cylindrical shape with radius of the base r and length h . The actual values of the dimensions r and h that guarantee the required volume of $V=7062 \text{ mm}^3$ are not critical, as long as the volume V does not deviate by more than $\Delta V = 20 \text{ mm}^3$ from the required value of $V=7062 \text{ mm}^3$. If the volume V deviates by more than 20 mm^3 from the required value, the subsequent processing of the workpiece will result in a faulty component. Suppose that the absolute errors in the radius r and the length h of the cylindrical workpieces are $\Delta r = \Delta h = 0.1 \text{ mm}$. The question of interest is estimating the dimensions r^* and h^* with which the pieces must be cut so that the absolute error ΔV^* in

the volume V is the smallest possible. In other words, the dimensions r^* and h^* are sought that correspond to an absolute error ΔV^* such that the inequality:

$$\Delta V \geq \Delta V^*$$

holds, where ΔV is an absolute error that corresponds to dimensions r and h , different from r^* and h^* but guaranteeing the required volume of $V=7062\text{mm}^3$.

Since the volume of the cylindrical pieces is $V = \pi r^2 h$, the absolute error associated with V is given by $\Delta V = \frac{\partial V}{\partial r} \Delta r + \frac{\partial V}{\partial h} \Delta h$, or

$$\Delta V = 2\pi r h \Delta r + \pi r^2 \Delta h \quad (15)$$

Substituting in (15) $\Delta r = \Delta h = 0.1\text{mm}$ yields

$$\Delta V = 0.2\pi r h + 0.1\pi r^2 \quad (16)$$

Since the nominal values of r and h which guarantee the required volume $V=7062\text{mm}^3$ are unknown, to find the minimum absolute error ΔV in the required volume V , the function

$$f(r, h) \equiv 0.2\pi r h + 0.1\pi r^2 \quad (17)$$

must be minimised under the constraint

$$g(r, h) \equiv \pi r^2 h - 7062 = 0 \quad (18)$$

The gradients of the functions $f(r, h)$ and $g(r, h)$ are:

$$\mathbf{grad} f(r, h) = (0.2\pi h + 0.2\pi r)\mathbf{i} + 0.2\pi r\mathbf{j} \quad (19)$$

where \mathbf{i} and \mathbf{j} are the unit vectors along the r and h axis

$$\mathbf{grad} g(r, h) = 2\pi r h \mathbf{i} + \pi r^2 \mathbf{j} \quad (20)$$

From $\mathbf{grad} f(r, h) = \lambda \mathbf{grad} g(r, h)$, the system of equations

$$0.2\pi(h+r) = \lambda 2\pi r h \quad (21)$$

$$0.2\pi r = \lambda \pi r^2 \quad (22)$$

is obtained.

Dividing the left and the right hand parts of the equations results in $(h+r)/r = 2h/r$, from which, it follows that $h^* = r^* = \sqrt[3]{V/\pi} = \sqrt[3]{7062/\pi} = 13.1$ is a critical point. From the contour plots of the functions $f(r, h)$ and $g(r, h)$, it can be verified that the critical point is the minimum.

Consequently,

$$\Delta V^* = 0.2\pi r h + 0.1\pi r^2 = 0.3\pi r^2 = 0.3 \times \pi \times 13.1 = 12.35.$$

This means that the inequality

$$\Delta V \geq \Delta V^*$$

has been proved regarding the absolute error ΔV associated with any other selected dimensions (r, h) which guarantee the required volume V .

The absolute error is smaller than 20mm^3 therefore, the workpieces with dimensions $r = h = 13.1\text{mm}$ dimensions will not result in defective components. By selecting the nominal dimensions $h^* = r^* = 13.1\text{mm}$ the deviation of the volume V due to errors in the dimensions (r, h) has effectively been bounded. This guarantees that the volume V cannot exceed a dangerous value and reliability cannot be compromised.

If for example, the dimensions $r = 14.1$ and $h = 11.31$ which deviate from the nominal values are selected, from

$$\Delta V = 2\pi r h \Delta r + \pi r^2 \Delta h = 2\pi \times 14.1 \times 11.31 \times 0.1 + \pi \times 14.1^2 \times 0.1 = 162.66 \text{ mm}^3 \quad (23)$$

it can be seen that the error in V significantly exceeds the maximum acceptable 20 mm^3 .

If the dimensions $r = 12.1$, $h = 15.35$ which also deviate from the nominal values are selected, from

$$\Delta V = 2\pi r h \Delta r + \pi r^2 \Delta h = 2\pi \times 12.1 \times 15.35 \times 0.1 + \pi \times 12.1^2 \times 0.1 = 162.69 \text{ mm}^3 \quad (24)$$

it can be seen that the error in V again significantly exceeds the maximum acceptable of 20 mm^3 .

3. Improving reliability and reducing risk by segmentation of loads and by chain-rule segmentation

The underlying idea of the method of segmentation is to prevent failure modes and reduce the vulnerability to a single failure, by dividing an entity into a number of distinct parts (Todinov, 2019).

In this section, it is demonstrated that combining domain-specific knowledge from strength of materials and the domain-independent method of segmentation could achieve an increase in reliability by increasing the resistance to overstress failure.

3.1 Reducing the risk of overstress failure by a segmentation of the external forces

It is not at all obvious that segmenting external loading forces could achieve a significant reduction of the internal stresses in a loaded structure. In the cases where engineers have

control over the design of the application points of external forces, a load segmentation can achieve a significant reduction of the internal stresses.

Consider the simply supported beam with length l and uniform cross section in Figure 1, loaded with a concentrated force P . From the bending moment diagram, in section $x=l/2$, the beam is subjected to a maximum moment $M_{\max,1} = Pl / 4$.

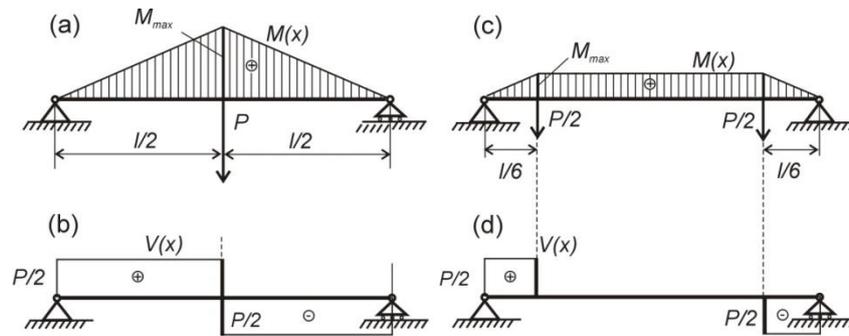


Figure 1. Reducing the risk of overstress failure of a beam by segmenting the external concentrated load P .

It is assumed that the design engineer has control over the application points of the external loads. Segmenting the concentrated load P into two concentrated loads with magnitudes $P/2$, applied at distances $l/6$ from the supports, reduces the maximum bending moment which, in turn, reduces the internal tensile stresses from bending. Reducing the magnitudes of the internal tensile stresses increases the resistance to overstress failure and therefore improves reliability. A similar reliability improvement effect is also present if external concentrated moments, instead of concentrated forces are segmented.

The load segmentation also improves reliability in the case of a horizontal concentrated external load. This mechanism will be illustrated by the example of a statically indetermined loaded bar in Figure 2a, loaded with the external concentrated load P .

The stresses in the different sections of the bar in Figure 2a can be determined by using an extra compatibility of displacements equation. This is a standard technique documented, for example, in (Gere and Timoshenko, 1999). Neglecting the weight of the bar, as being much smaller compared to the magnitude of the concentrated force P , the stresses acting in the parts

AC and CB of the bar are $\sigma_{AC} = \frac{P}{2A}$ and $\sigma_{BC} = -\frac{P}{2A}$, correspondingly (Figure 2b).

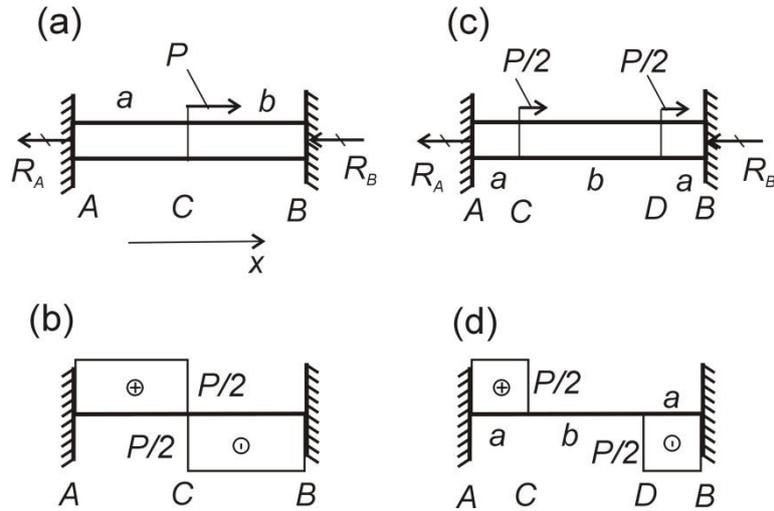


Figure 2. Reducing the overstress failure of a statically indeterminate bar by segmenting the external load

Now if the original concentrated load P is segmented into two loads, each with magnitude $P/2$, applied at the same distances a from the supports (Figure 2c), the stresses acting in the parts AC and DB of the bar are still $\sigma_{AC} = \frac{P}{2A}$ and $\sigma_{DB} = -\frac{P}{2A}$, correspondingly, but the stress in any section of the part CD with length ' b ' is now zero (Figure 2d). This means that because of the reduced length where internal stresses are excited, the probability of failure due to buckling is reduced and the probability of failure due to a presence of a flaw in the material is also reduced.

Finally, consider the more complex truss structure in Figure 3a loaded by a 6kN external force. It is assumed again that the designer can control the points of application for the external load. The forces in the separate members have been calculated by the standard *method of sections* (Hibbeler, 2004) and are given in Table 1. The tensile forces are with plus sign while the compressive forces are with a negative sign.

As can be verified from Table 1, the loading with a single (non-segmented) force (Figure 3a) resulted in higher stresses in the members of the truss. Thus, the largest load for the truss with non-segmented load is 7.5kN (Table 1) while the largest load for the truss with segmented force is 5.25kN (Table 1). In addition, the magnitudes of the loads in the truss with segmented external load (Figure 3b) are more uniform compared with the truss with non-segmented external load (Figure 3a). Indeed, the average value of the absolute values of the forces for the truss in Figure 3a is 4.91kN and the standard deviation of the absolute magnitudes of the forces is 2kN. In contrast, the average value of the absolute values of the

forces for the truss with segmented external load (Figure 3b) is 3.31kN and the standard deviation of the absolute magnitudes of the forces is 1.12kN.

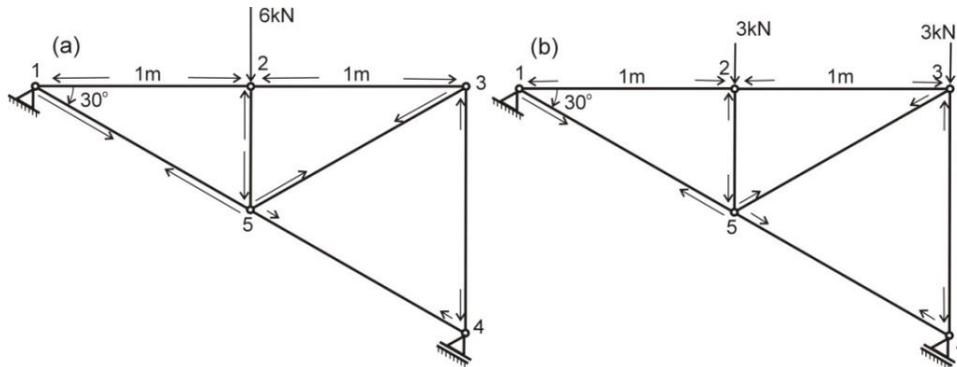


Figure 3. Reducing the overstress failure of a truss by segmenting the external load

Table 1 Forces calculated in the truss by the method of sections.

Force [kN]	S_{12}	S_{15}	S_{23}	S_{25}	S_{34}	S_{35}	S_{45}
Truss (a)	-5.196	+7.5	-5.196	-6	-3	+6	+1.5
Truss (b)	-2.59	+5.25	-2.59	-3	-4.5	+3	+2.25

The presented simple solution for reducing the stresses in loaded structures based on segmentation has never been suggested in standard textbook on stress analysis and strength of components (Hearn 1985; Budynas, 1999; Gere and Timoshenko, 1999; Budynas and Nisbett 2015; Collins 2003; Norton, 2006). This shows that the lack of knowledge of the domain-independent method of segmentation made it invisible to the domain-specific experts that segmenting external loads can be used to reduce the internal stresses in a loaded structure and to reduce its risk of failure.

3.2 Reducing the risk of computational errors by the method of chain-rule segmentation

Segmentation is a universal domain-independent concept for risk reduction and can even be applied in the distant area related to reducing the risk of computational errors.

In this section, domain-specific knowledge from kinematic analysis of mechanisms and the domain-independent method of segmentation through the chain rule are combined to achieve a decrease in the risk of computational errors.

The chain rule for differentiation of a function of a function is a well-known concept (Ellis and Gulick, 1991). The idea behind the concept of reducing errors by a segmentation through the chain rule is described next.

Suppose that a process output is a complex continuous function $y = y(x)$ of the input parameter x . Finding the derivative $\frac{dy}{dx}$ which describes the process output rate is often difficult and associated with a large likelihood of errors because of the complex function $y = y(x)$. The direct differentiation, if at all practicable, often leads to enormous, very complex expressions, during whose derivation the likelihood of making an error is very high. These difficulties disappear if segmentation through the chain rule is applied. The complex continuous function $y = y(x)$ is segmented into several simpler functions. Suppose that y is expressed as a continuous function $y(u_1)$ of the parameter u_1 ; the parameter u_1 is expressed as a continuous function $u_1(u_2)$ of the parameter u_2 and so on, until a parameter u_n is reached, which is expressed as a simple function $u_n(x)$ of x . As a result, $y = y(x)$ is effectively segmented to a nested composition of several functions:

$$y = y(u_1(u_2(u_3(\dots u_n(x)))))) \quad (25)$$

Applying the chain rule, for the derivative dy/dx , of the expression (25) gives

$$\frac{dy}{dx} = \frac{dy}{du_1} \times \frac{du_1}{du_2} \times \frac{du_2}{du_3} \times \dots \times \frac{du_n}{dx} \quad (26)$$

Expression (26) is effectively a segmentation of the complex derivative dy/dx into derivatives dy/du_1 , du_1/du_2 , du_n/dx whose evaluation is relatively easy. Reducing the risk of errors comes from the circumstance that the evaluation of the separate derivatives $\frac{du_i}{du_{i+1}}$ is associated with a significantly smaller likelihood of error than the evaluation of the

original derivative $\frac{dy}{dx}$. The complex task related to determining the rate $\frac{dy}{dx}$ has effectively been replaced by a number of sub-tasks with easy solutions. The solution of the original problem is assembled by multiplying the solutions of the partial problems, which is a straightforward operation. By making the differentiation of a complex expression easy through the chain-rule segmentation, the likelihood of errors is reduced significantly.

The method of chain-rule segmentation remains the same if some of the parameters depend not on a single parameter but on two or more parameters. In this case, partial derivatives are used.

This chain-rule segmentation method will be illustrated with an example related to the specific domain "kinematic analysis of complex mechanisms". The mechanism in Fig.4, whose kinematics is to be modelled, incorporates a primary slider B and a secondary slider D connected to the primary slider by the rod CD , the pin joint C and the link CB . The link CB is welded firmly to the primary slider B as shown in the figure and remains always perpendicular to the link AT . The crank PA rotates in clockwise direction, with a uniform angular velocity of $\omega = 2 \text{ rad/s}$. The crank PA subtends an angle φ with the vertical axis and varies within the interval $[0, 2\pi]$ ($0 \leq \varphi \leq 2\pi$). The values of the parameters fully specifying the mechanism are as follows:

$$PA = r = 0.35m ; CB = s = 0.65m ; CD = m = 0.75m ; OP = p = 0.60m ; OB = d = 0.85m$$

By using trigonometry, the coordinate $y = y(t)$ of point D can be expressed as:

$$y(t) = d + s \times \frac{p - r \cos(\omega t)}{\sqrt{[p - r \cos(\omega t)]^2 + [d + r \sin(\omega t)]^2}} + \sqrt{m^2 - \frac{s^2 [d + r \sin(\omega t)]^2}{[p - r \cos(\omega t)]^2 + [d + r \sin(\omega t)]^2}} \quad (27)$$

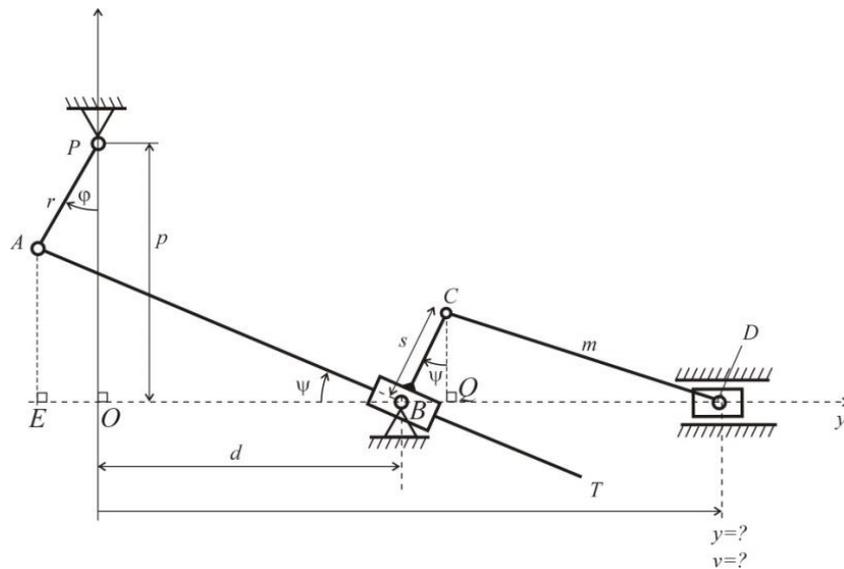


Figure 4. A mechanism whose kinematic analysis benefits from segmenting the problem through the application of the chain rule.

Differentiating expression (27) directly with respect to t in order to determine the time dependence of the velocity of the slider D ($v(t) = dy(t) / dt$) leads to a very complex expression, in whose derivation the likelihood of errors is very high.

However, $y(t)$ can be presented as a nested composition of three functions:

$$y(t) = y(\psi(\varphi(t))),$$

each of which is easy to define:

$$y(\psi) = d + s \times \sin \psi + \sqrt{m^2 - s^2 \cos^2 \psi} \quad (28)$$

$$\psi(\varphi) = \tan^{-1} \left(\frac{p - r \cos \varphi}{d + r \sin \varphi} \right) \quad (29)$$

and $\varphi(t) = \omega t$.

Now the evaluation of the complex derivative $v(t) = dy(t) / dt$ is segmented by using the chain rule:

$$dy(t) / dt = [dy / d\psi] \times [d\psi / d\varphi] \times [d\varphi / dt] \quad (30)$$

Combining the derivatives by using the chain rule (26), results in

$$dy / dt = \left[s \cos \psi + \frac{s^2 \sin(2\psi)}{2\sqrt{m^2 - s^2 \cos^2 \psi}} \right] \times \frac{r^2 + rd \sin \varphi - pr \cos \varphi}{r^2 + d^2 + p^2 + 2dr \sin \varphi - 2pr \cos \varphi} \times \omega \quad (31)$$

where the angle ψ is given by the expression (29).

As a result, the chain-rule segmentation method avoids the difficult direct differentiation of expression (27) where the likelihood of making errors is significant. This is a powerful application of the method of segmentation in reducing the likelihood of computational errors while determining the rate of complex processes.

The graphs presenting the displacement and velocity of slider D are given in Fig.5.

The correctness of the proposed chain-rule segmentation method (analytical expression (31)) in determining the velocity of the second slider, has been verified by using a direct (numerical) differentiation of expression (27) by discretising the angle $0 \leq \varphi \leq 2\pi$ into small steps $h = 0.001 \text{ rad}$. The value of the velocity for any time t is given by

$$v(t) \equiv dy / dt = (dy / d\varphi) \times (d\varphi / dt) \quad (32)$$

Since $dy / d\varphi$ at an angle φ_i can be approximated numerically by

$$(dy / d\varphi) |_{\varphi=\varphi_i} \approx \frac{y(\varphi_{i+1}) - y(\varphi_i)}{h}, \quad (33)$$

Consequently

$$v_i \approx \frac{y(\varphi_{i+1}) - y(\varphi_i)}{h} \times \omega \quad (34)$$

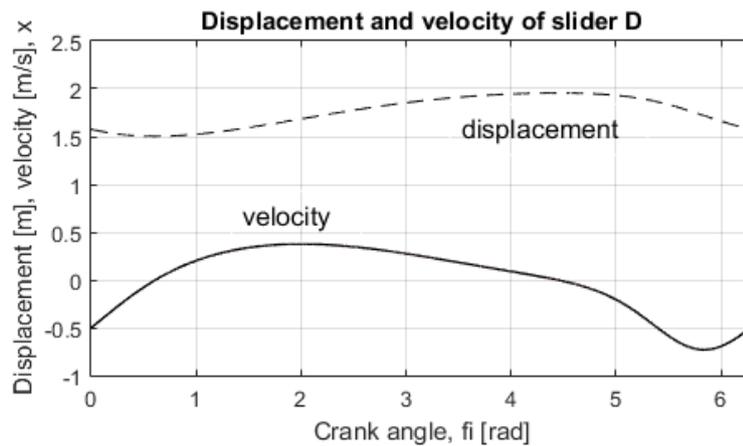


Figure 5. The velocity of slider D obtained from the chain-rule segmentation method coincide with the velocity obtained from a direct numerical differentiation.

The results from the numerical differentiation for the velocity of slider D coincide with the results for the velocity of slider D calculated from the chain-rule segmentation method. The excellent correspondence of results obtained by two principally different methods validates the chain-rule segmentation method for reducing the risk of computational errors and demonstrates its validity.

To the best of our knowledge, the chain rule segmentation technique has not been discussed as a powerful analytic method for reducing the risk of computational errors in the analysis of complex mechanisms and machines (Uicker et al., 2017; Dicker et al, 2003; Sandor and Erdman, 1984). This example also demonstrates that the lack of knowledge of the method of segmentation made it invisible to experts that chain rule segmentation can be used with great success to reduce the risk of errors in complex calculations.

CONCLUSIONS

- A powerful domain-independent method for improving reliability and reducing risk based on algebraic inequalities has been introduced.

- A major advantage of algebraic inequalities has been demonstrated in ranking decision strategies in the absence of any knowledge related to the individual building elements.

If no information about the component reliability characterising the individual suppliers is available, purchasing components from a single supplier or from the smallest possible number of suppliers maximises the probability of a high-reliability assembly.

- A major advantage of algebraic inequalities has been demonstrated in limiting the variation of a critical output parameter caused by variation of the design variables.
- The presented methods for risk reduction transcend mechanical engineering and work in many unrelated domains. The benefits from combining domain-independent methods with domain-specific knowledge to achieve risk reduction have been demonstrated in four unrelated application domains: decision-making, manufacturing, strength of components and kinematic analysis of mechanisms.
- A powerful chain-rule segmentation method for reducing the likelihood of computational errors during determining the rate of complex processes has been introduced and demonstrated in the area of kinematics analysis of complex mechanisms.
- Segmenting external loads can improve significantly the resistance to overstress failure by reducing the magnitudes of the internal stresses in loaded structures.

The presented research can be continued with: (i) new applications of algebraic inequalities for improving reliability and reducing risk; (ii) new applications demonstrating the benefits from combining domain-independent methods with specific knowledge in a particular domain to achieve effective risk reduction and (iii) developing new domain-independent methods for reliability improvement and risk reduction.

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